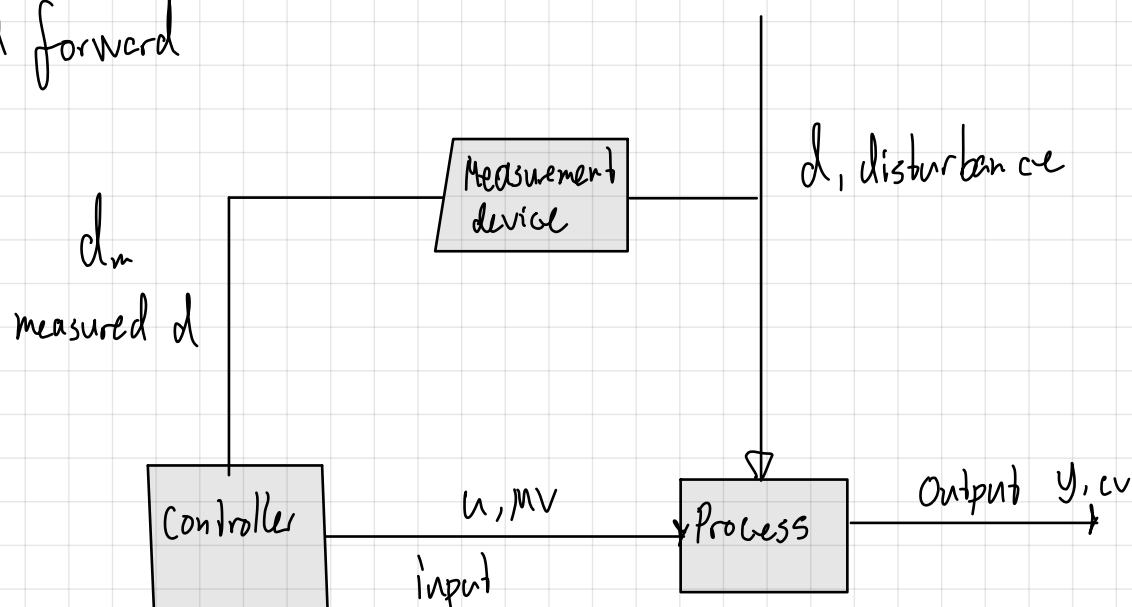
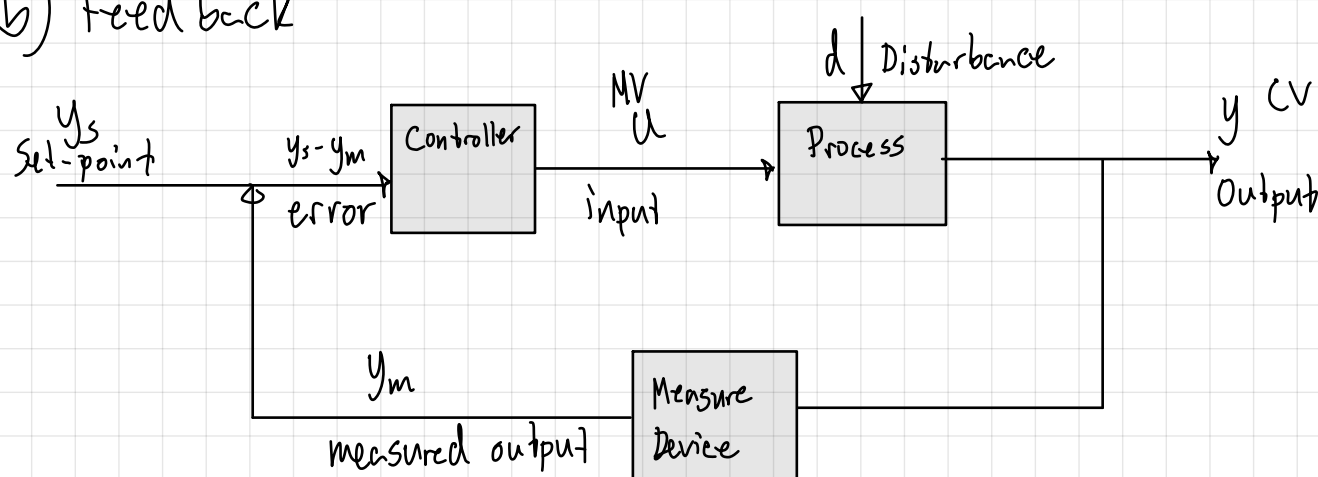


a) Feed forward



- The disturbance d is measured
- The controller adjusts the input in order to counteract the effect of the disturbance

b) Feed back



- The output of the process is measured (y)
 - ↳ The output is compared to a set value (y_s)
 - ↳ The error is given to a controller unit
 - ↳ The controller unit then adjust an input (u) to minimize the error